# Metric Interval Temporal Logic Revisited 

MOVE seminar

Benjamin Monmege (LIF, Aix-Marseille Université)
Based on joint works with
Thomas Brihaye, Hsi-Ming Ho, Morgane Estiévenart (UMONS),
Gilles Geeraerts (ULB), and Nathalie Sznajder (LIP6)

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## Timed systems



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This is a timed automaton.

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- Pointwise (event-based) view: timed word

$$
(\text { MoveUp, 1)(Arrive, 6)... }
$$

- Continuous (state-based) view: signal from $\mathbb{R}_{\geqslant 0}$ to states

|  | OF |  | 0_TO_1 |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0 | 1 | 1 | 1 | 1 | 1 |  | 1F |  |
| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |  |

Metric Temporal Logic (MTL)

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\varphi::=\top|a| \neg \varphi|\varphi \wedge \varphi| \varphi \mathrm{U}_{I} \varphi
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with $a \in \Sigma, I \subseteq[0, \infty)$ with bounds in $\mathbb{N} \cup\{+\infty\}$.

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In the pointwise semantics:
$\varphi_{1} U_{1} \varphi_{2}$$\varphi$
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\diamond\left(\text { Move } U p \wedge \diamond_{[5,5]} \text { Arrive }\right)
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3. Synthesise a valid system from an MTL specification, under certain restrictions on the environment

- reactive synthesis task


## Part 1: satisfiability and model-checking

Based on a joint work with Thomas Brihaye (UMONS), Gilles Geeraerts (ULB), and Hsi-Ming Ho (UMONS)


Submitted at CAV 2017 @ Heidelberg

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Can we find a fully decidable subclass?

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Satisfiability and model checking for ECL are PSPACE-complete.

## Theorem: [Wilke, 1994, Henzinger et al., 1998]

ECL with projection (i.e. outermost second-order quantification) is equally expressive as timed automata.

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- Model checking networks of timed automata against a fragment of TCTL
- a pretty restricted fragment, but at least reachability is supported
- The de facto standard tool for timed automata

UPPAAL in a nutshell
KG Larsen, PPettersson, WYii - International journal on software tools for ..., 1997 - Springer Abstract. This paper presents the overal structure, the design criteria, and the main features of the tool box Uppaal. It gives a detailed user guide which describes how to use the various tools of Uppaal version 2.02 to construct abstract models of a real-time system, to simulate Cited by 2153 Related articles All 18 versions Cite Save

A tutorial on uppaal
G Behrmann, A David, KG Larsen - Formal methods for the design of real- ..., 2004 - Springer Abstract This is a tutorial paper on the tool Uppaal. Its goal is to be a short introduction on the flavor of timed automata implemented in the tool, to present its interface, and to explain how to use the tool. The contribution of the paper is to provide reference examples and
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Tool support for MITL

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Construction for $\mathrm{ECL}\left(\equiv \mathrm{MITL}_{0, \infty}\right)$ much simpler and adaptable to the pointwise semantics [Henzinger, 1998].
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Still, most LTL-to-BA constructions are monolithic : difficult to modify them to incorporate time.
Other direction of research: usage of SMT solvers [Bersani, Rossi, and San Pietro, 2015, Kindermann, Junttila, and Niemelä, 2013, Woźna-Szcześniak, Szcześniak, M. Zbrzezny, and Zbrzezny, 2014]

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This work:

- Compositional
- Less states (subsumes [Gastin and Oddoux, 2001])
- Less clocks
- Works well with Uppaal!

From LTL to alternating automata [Vardi, 1998]

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\square(a \Rightarrow \Delta b)
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\square(a \Rightarrow \diamond b)
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A run on $a a a b:$


## From alternating automata to non-deterministic automata

Theorem: [Miyano and Hayashi, 1984]
An alternating Büchi automaton with $n$ locations can be translated into a non-deterministic Büchi automaton with $3^{n}$ locations.

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The tool LTL2BA is still in wide use today.

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How to synchronise these components?

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## Proposition:

If $\mathcal{C}_{\varphi_{1} \mathcal{U} \varphi_{2}}$ accepts a (timed) word $\rho$ then $\rho \models \square\left(p_{\varphi} \Rightarrow \varphi_{1} \mathcal{U} \varphi_{2}\right)$.

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## Proposition:

For each LTL formula $\varphi$ over AP, we can construct a Büchi automaton $\mathcal{A}_{\varphi}=\mathcal{C}_{\psi_{1}} \times \cdots \times \mathcal{C}_{\psi_{n}}$ over AP $\cup \mathrm{AP}^{\prime}$ such that $\mathcal{L}(\varphi)=\mathcal{L}\left(\operatorname{proj}_{\mathrm{AP}}\left(\mathcal{A}_{\varphi}\right)\right)$.

## Compositional Gastin-Oddoux: full example

$\varphi=\square(p \Rightarrow \diamond q) \equiv \perp \mathcal{R}(\neg p \vee \top \mathcal{U} q)$

$$
\begin{aligned}
& \rightarrow 1 p_{\varphi} \rightarrow \neg p_{\varphi} \\
& \neg p_{\varphi} \wedge \neg p_{\diamond q} \cap 0 p_{\varphi} \wedge\left(\neg p \wedge \neg p_{\diamond q} \vee p \wedge p_{\diamond q}\right) \sim \neg p \wedge \neg p_{\diamond q} \vee p \wedge p_{\diamond q}
\end{aligned}
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A run on $(a, 0.5)(a, 0.6)(a, 1.2)(b, 2.3)$ :


In this case we can simply keep the 'oldest' $\diamond$.

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E.g., $\mathcal{C}_{\varphi_{1} \mathcal{U}_{[2, \infty]} \varphi_{2}}$ :

$\neg p_{\chi} \wedge \varphi_{1} \wedge \neg \varphi_{2}$
$\neg p_{\chi} \wedge \varphi_{1} \wedge x<2$
$p_{\chi} \wedge \varphi_{1}$
$p_{\chi} \wedge \varphi_{1} \wedge \varphi_{2} \wedge x \geqslant 2, x:=0$

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E.g., $\mathcal{C}_{\varphi_{1} \mathcal{U}_{[2, \infty]} \varphi_{2}}$ :


## Proposition:

For each $\mathrm{MITL}_{0, \infty}$ formula $\varphi$ with $n$ timed subformulas, we can construct a projection-equivalent timed automaton $\mathcal{A}_{\varphi}$ that uses $n$ clocks.

## Full MITL: inspired by interval semantics for OCATA

New semantics for OCATA [Brihaye, Estiévenart, and Geeraerts, 2013]:

- allows one to bound the number of clock copies
- sufficiently expressive for MITL


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New semantics for OCATA [Brihaye, Estiévenart, and Geeraerts, 2013]:

- allows one to bound the number of clock copies
- sufficiently expressive for MITL

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0.3
1.3

To check that this timed word satisfies $\varphi$, we do not need to remember the exact timestamp of each $a$

## Example run with the interval semantics



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$\varphi=\varphi_{1} \mathcal{U}_{[a, b]} \varphi_{2}$, with $0<a<b<+\infty$ : improvement on the interval semantics

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Case 1: $\{1,2,3\}$
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Case 3: $\{1,2\},\{3\}$
Case 4: $\{1,2\},\{2,3\}$ or $\{1,2,3\},\{2,3\}$
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In each case we only need to keep track of two clock values.
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Case 1: Another branching into Case 1, Case 3 and Case 4
Case 2: Done
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## Proposition:

For each MITL formula $\varphi=\varphi_{1} \mathcal{U}_{1} \varphi_{2}, \mathcal{C}_{\varphi}$ uses $2 \cdot\left\lceil\frac{\text { sup } I}{\|I\|}\right\rceil+2$ clocks.
Up to half the number of clocks obtained in [Brihaye, Estiévenart, and Geeraerts, 2014]

## Experiments

We have implemented the translation in the tool MightyL.

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\begin{aligned}
F(k, I) & =\bigwedge_{i=1}^{k} \diamond_{I} p_{i} \\
U(k, I) & =\left(\cdots\left(p_{1} \mathcal{U}_{I} p_{2}\right) \mathcal{U}_{l} \cdots\right) \mathcal{U}_{I} p_{k} \\
\theta(k, I) & =\neg\left(\left(\bigwedge_{i=1}^{k} \square \diamond p_{i}\right) \Rightarrow \square\left(q \Rightarrow \nabla_{I} r\right)\right)
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$$
\begin{aligned}
G(k, I) & =\bigwedge_{i=1}^{k} \square_{I} p_{i} \\
R(k, I) & =\left(\cdots\left(p_{1} \mathcal{R}_{I} p_{2}\right) \mathcal{R}_{I} \cdots\right) \mathcal{R}_{I} p_{k} \\
\mu(k) & =\bigwedge_{i=1}^{k} \diamond_{[3(i-1), 3 i]} t_{i} \wedge \square \neg p
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$$

| Formula | MIGHTYL | LTSMIN | UPPAAL |
| :---: | :---: | :---: | :---: |
| $F(5,[0, \infty))$ | 9 ms | $3.48 \mathrm{~s} / 2.18 \mathrm{~s} / 0.12 \mathrm{~s}$ | 0.75 s |
| $F(5,[0,2])$ | 7 ms | $3.76 \mathrm{~s} / 2.23 \mathrm{~s} / 0.15 \mathrm{~s}$ | 0.84 s |
| $F(5,[2, \infty))$ | 6 ms | $3.76 \mathrm{~s} / 2.26 \mathrm{~s} / 0.91 \mathrm{~s}$ | 1.64 s |
| $F(3,[1,2])$ | 70 ms | $6 \mathrm{~m} 5.15 \mathrm{~s} / 38.01 \mathrm{~s} / 0.22 \mathrm{~s}$ | 9.00 s |
| $F(5,[1,2])$ | 70 ms | $>15 \mathrm{~m}$ | 2 m 6 s |
| $G(5,[0, \infty))$ | 10 ms | $3.83 \mathrm{~s} / 2.43 \mathrm{~s} / 0.05 \mathrm{~s}$ | 0.75 s |
| $G(5,[0,2])$ | 10 ms | $4.01 \mathrm{~s} / 2.51 \mathrm{~s} / 0.10 \mathrm{~s}$ | 0.82 s |
| $G(5,[2, \infty))$ | 9 ms | $4.06 \mathrm{~s} / 2.47 \mathrm{~s} / 0.04 \mathrm{~s}$ | 0.85 s |
| $G(5,[1,2])$ | 15 ms | $7.81 \mathrm{~s} / 2.99 \mathrm{~s} / 0.09 \mathrm{~s}$ | 1.12 s |
| $\mu(1)$ | 13 ms | - | 0.39 s |
| $\mu(2)$ | 21 ms | - | 2.33 s |
| $\mu(3)$ | 76 ms | - | 15.77 s |
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| $U(5,[0, \infty))$ | 16 ms | $1.90 \mathrm{~s} / 1.44 \mathrm{~s} / 0.05 \mathrm{~s}$ | 0.41 s |
| $U(5,[0,2])$ | 8 ms | $2.08 \mathrm{~s} / 1.54 \mathrm{~s} / 0.06 \mathrm{~s}$ | 0.42 s |
| $U(5,[2, \infty))$ | 8 ms | $2.08 \mathrm{~s} / 1.5 \mathrm{~s} / 0.09 \mathrm{~s}$ | 0.52 s |
| $U(,[1,2])$ | 49 ms | $4 \mathrm{~m} 0.14 \mathrm{~s} / 23.54 \mathrm{~s} / 0.09 \mathrm{~s}$ | 4.92 s |
| $U(5,[1,2])$ | 97 ms | $>15 \mathrm{~m}$ | 21.80 s |
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| $\theta(1,[100,1000])$ | 9 ms | $1.88 \mathrm{~s} / 1.74 \mathrm{~s} / 0.04 \mathrm{~s}$ | 0.25 s |
| $\theta(2,[100,1000])$ | 13 ms | $5.04 \mathrm{~s} / 3.17 \mathrm{~s} / 0.19 \mathrm{~s}$ | 0.86 s |
| $\theta(3,[100,1000])$ | 14 ms | $36.57 \mathrm{~s} / 16.27 \mathrm{~s} / 3.20 \mathrm{~s}$ | 21.84 s |
| $\theta(4,[100,1000])$ | 15 ms | $5 \mathrm{~m} 30 \mathrm{~s} / 4 \mathrm{~m} 18 \mathrm{~s} / 2 \mathrm{~m} 16 \mathrm{~s}$ | 18 m 39 s |

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| :---: | :---: | :---: | :---: | :---: |
| $\diamond_{[0,30]}\left(p \Rightarrow \square_{[0,20]} p\right)$ valid | 7 ms | 0.98 s | 0.32 s | 7 s |
| $\square_{[0,30]} \neg p \vee \diamond_{[0,20]} p$ valid | 7 ms | 0.95 s | 0.14 s | not considered |
| $\diamond_{[0,30]} p \wedge \diamond_{[0,20]} p$ redundant | 13 ms | 1.99 s | 0.44 s | 14 s |
| $\square_{[0,20]} \diamond_{[0,20]} p \wedge \square_{[0,40]} p \wedge \diamond_{[20,40]} \top$ redundant | 22 ms | 1 m 26 s | 2.63 s | not considered |

## Summary for the satisfiability/model-checking of MITL

Contributions:

- A compositional translation from MITL to timed automata
- An implementation that works with UppaAL and the like


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Possible future directions:

- Native support for ECL
- Past modalities, counting modalities
- Antichain-based optimisations
- ...


## Part 2: reactive synthesis

Based on a joint work with Thomas Brihaye (UMONS), Morgane Estiévenart (UMONS), Gilles Geeraerts (ULB), Hsi-Ming Ho (UMONS) and Nathalie Sznajder (LIP6, UPMC)


Published at FORMATS 2016 @ Quebec City

## Reactive synthesis

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\Sigma=\Sigma_{C} \uplus \Sigma_{E}
$$

- controllable actions owned by controller C: \{MoveUp, MoveDown, OpenDoor, Opened, . . .\}
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## Reactive synthesis

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( $\Delta_{E}$, Open)

Only action(s) with the shortest delay $\min \left(\Delta_{C}, \Delta_{E}\right)$ may be played.

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Given plant $\mathcal{P}$ and specification $\mathcal{L}$, find a strategy of Controller such that no matter what Environment does, every play satisfies the specification.

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Realizability problem: the special case where all actions are always enabled, i.e., $\mathcal{P}$ is a universal DTA over $\Sigma$.

## Metric Temporal Logic (MTL)

$$
\varphi::=\top|a| \neg \varphi|\varphi \wedge \varphi| \varphi \mathrm{U}_{1} \varphi
$$

with $a \in \Sigma, I \subseteq[0, \infty)$ with bounds in $\mathbb{Q} \cup\{+\infty\}$
Models: finite (or infinite) timed words $\sigma=\left(a_{1}, t_{1}\right)\left(a_{2}, t_{2}\right) \cdots$


## Theorem: [Doyen, Geeraerts, Raskin, and Reichert, 2009]

Reactive synthesis problem is undecidable for ECL (hence, MTL) specifications, even without plant.

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Let $\mathcal{P}$ be a universal plant, and the spec be
'Each a is followed exactly 1 t.u. later by a b.'

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Theorem: [Doyen, Geeraerts, Raskin, and Reichert, 2009]
The infinite-word realizability problem is undecidable for ECL specifications.

## Implementable reactive synthesis (IRS)

$\mathrm{C}=$ deterministic symbolic transition system $\mathcal{T}$

- set of locations; if finite $\rightarrow \mathcal{T}$ is a DTA
- finite set of clocks
- finite set of possible clock constraints precision ( $m, K$ ):

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\begin{aligned}
& g::=\top|g \wedge g| x<\alpha / m|x \leqslant \alpha / m| x=\alpha / m|x \geqslant \alpha / m| x>\alpha / m \\
& \text { with } x \in X, m \in \mathbb{N} \text { and } 0 \leqslant \alpha \leqslant K
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## Definition

Implementable reactive synthesis problem (IRS): Given $\mathcal{P}$ and $\mathcal{L}$, find such a $\mathcal{T}$ that no matter what $E$ does, every play satisfies the specification.

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NOT CONTROLLABLE for IRS

- each $\mathcal{T}$ has a bounded set of clocks


## Reactive synthesis for MTL

Reactive synthesis Undec. [Doyen, Geeraerts, Raskin, and Reichert, 2009]

## Reactive synthesis for MTL



## Recovering decidability...

Clock constraints in $\mathcal{T}$ :

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Fix $X$ and $(m, K) \Longrightarrow$ the alphabet of $\mathcal{T}$ is given!

## Definition

Bounded-resources reactive synthesis problem (BResRS): Given $\mathcal{P}, \mathcal{L}$, and a set of clocks $X$ and precision ( $m, K$ ), find such a resource-bounded $\mathcal{T}$ that no matter what $E$ does, every play satisfies the specification.

## Reactive synthesis for MTL

| Reactive synthesis Undec. [Doyen, Geeraerts, Raskin, and Reichert, 2009] |  |
| :--- | :--- |
|  | Controller = timed automaton |
| Implementable reactive synthesis $\quad$ Undec. [Bouyer, Bozzelli, and Chevalier, 2006] |  |

## Reactive synthesis for MTL



Clocks- and precision-bounded reactive synthesis
Dec. \& Non-elem. over finite words [Bouyer, Bozzelli, and Chevalier, 2006]

## Reactive synthesis for MTL



## Reactive synthesis for MTL



## Regaining hope? Less expressive specifications

Undecidability proofs heavily use 'punctuality' of MTL: request $\rightarrow\rangle_{=1}$ grant

$$
\begin{gathered}
\text { request } \rightarrow \diamond_{[1,2]} \text { grant } \\
\text { request } \rightarrow \diamond_{\leqslant 3} \text { grant }
\end{gathered}
$$

MITL $=$ non-punctual fragment of MTL:

$$
\varphi::=\top|a| \neg \varphi|\varphi \wedge \varphi| \varphi \mathrm{U}_{I} \varphi
$$

with $a \in \Sigma, I \subseteq[0, \infty)$ is a non-singular with bounds in $\mathbb{Q} \cup\{+\infty\}$

## Contribution: reactive synthesis for MITL



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## From MTL to OCATA

$$
\varphi=\square(a \Rightarrow \Delta[[1,2]] b)
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Execution on the timed word $(a, 0.5)(a, 0.6)(a, 1.2)(b, 2.3)$ :


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- Action ( $a, g, R$ )
- a: an action in $\Sigma_{C} \cup \Sigma_{C}$
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- If tree finite and winning strategy: we have a (finite) controller $\mathcal{T}$


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- Complexity: non-primitive recursive due to well-quasi orderings


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- Experimental results on a scheduling problem

| Realisable instances |  |  |  |
| :---: | :---: | :---: | :---: |
| $T$ | $n$ | \# clocks | exec. time $(\mathrm{sec}) /$ \#nodes |
| 1 | 1 | 0 | $46 / 52$ |
| 1 | 1 | 1 | $199 / 147$ |
| 1 | 1 | 2 | $4,599 / 1,343$ |
| 2 | 2 | 1 | $2,632 / 645$ |
| 2 | 2 | 2 | $18,453 / 2,358$ |
| 3 | 3 | 1 | $182,524 / 2,297$ |
| 3 | 3 | 2 | $>5 \min$ |
| 4 | 4 | 0 | $54,893 / 667$ |
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| Unealisable instances |  |  |  |
| :--- | :---: | :---: | :---: |
| $T$ | $n$ | \# clocks | exec. time (sec)/\#nodes |
| 2 | 1 | 0 | $77 / 84$ |
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| 3 | 2 | 1 | $17,134 / 1698$ |
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- This was before MightyL, which could make things easier...


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Possible future directions:

- Decidable fragments for BPrecRS/BClockRS
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> Thank you for your attention! Questions?

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