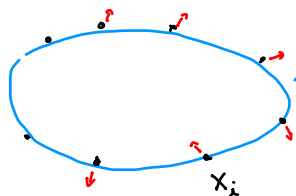


TD / TP 3

Ex. 3



$$g \cdot (a_1 x^2 + a_2 y^2 + a_3 z^2 + a_4 xy + a_5 xz + a_6 yz + a_7 x + a_8 y + a_9 z = 1)$$

inconnus: $(a_i) \leftrightarrow$ surface
 \downarrow
 g inconnus.

syst - g inconnus
 \downarrow
 g eq \leftrightarrow g pts x_i

Syst:

$$\forall x_i \rightarrow \begin{cases} \vdots \\ a_1 x_i^2 + a_2 y_i^2 + a_3 z_i^2 + a_4 x_i y_i + a_5 x_i z_i + a_6 y_i z_i + a_7 x_i + a_8 y_i + a_9 z_i = 1 \\ \vdots \end{cases} \leftarrow i$$

g eq \downarrow g inconnus
 $w = \begin{pmatrix} a_1 \\ \vdots \\ a_9 \end{pmatrix}$

syst. linéaire
 \downarrow
 $Xw = y$

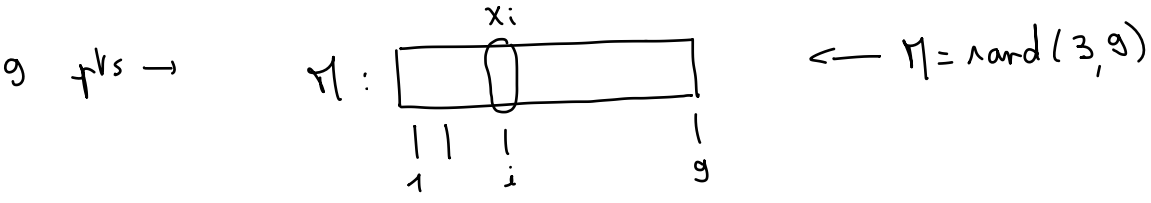
$Xw = y$

$$X = \begin{pmatrix} \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ x_i^2 & y_i^2 & z_i^2 & x_i y_i & x_i z_i & y_i z_i & x_i & y_i & z_i \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{pmatrix} \leftarrow g \times g$$

$$y = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} \leftarrow g \times 1$$

Résoudre en Matlab: $w = X \backslash y$

Pts \rightsquigarrow matrice M par col



plotImplicit3D (f , min BB , max BB , step BB)

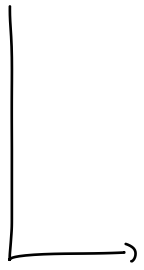
↙
prenant
en arg
 x, y, z
vechs de
coords
et calculant
f en //
(. *)

plot3D

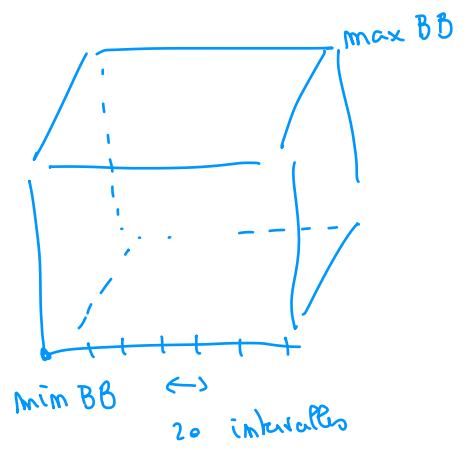
↘
limites
de la
boite
englobante
de representation

plot-entier-3D

↘
nbr de
seg. selon x, y, z



plotImplicit3D (f , [-1, -1, -1] , [1, 1, 1] , [20, 20, 20])



Script

```
clear
clc
clf
hold on

addpath('MarchingCubes')

N = 9 ;
M = rand(3,N) ;
eps = 10/100. ;

f = compute_quad(M) ;

% Représentation graphique
window = 1.5 ;

plotImplicit3D(f, [-window, -window, -window], [window, window, window], [20, 20, 20]) ;
plot3(M(1,:), M(2,:), M(3,:), 'g', 'MarkerSize',20) ;

% Perturbation des points

delta = (rand(size(M))-0.5)*2*eps ;
M = M+delta ;
f2 = compute_quad(M) ;

% Représentation graphique

plotImplicit3D(f2, [-window, -window, -window], [window, window, window], [20, 20, 20]) ;
plot3(M(1,:), M(2,:), M(3,:), 'r', 'MarkerSize',20) ;
```

Fonction compute_quad

```
function [f] = compute_quad(M)
    N = size(M,2) ;
    X = [(M(1,:)).^2, (M(2,:)).^2, (M(3,:)).^2, (M(1,:)).*(M(2,:)), (M(1,:)).*(M(3,:)), ...
        (M(2,:)).*(M(3,:)), M(1,:), M(2,:), M(3,:)] ;
    y = ones(N, 1) ;
    disp(cond(X))

    % Résolution
    w = X\y ; % a1, a2 .....

    % Reconstruction de la fonction f

    f = @(x,y,z) w(1)*x.^2 + w(2)*y.^2 + w(3)*z.^2 + w(4)*x.*y + w(5)*x.*z + ...
        w(6)*y.*z + w(7)*x + w(8)*y + w(9)*z - 1 ;
end
```

TD → ex 1, 2, 5

GSL → GNU scientific library ↔ Matlab C/C++

Linear algebra - Eigen → BLAS
Matrix C/C++ / JAVA / Python ...



Ex. 1

1) We get

$$A = \begin{pmatrix} d_1 & & & & & \\ & \ddots & & & & \\ & & \ddots & & & \\ & & & \ddots & & \\ & & & & \ddots & \\ & & & & & d_m \end{pmatrix}$$

10^{-3} (pointing to d_1)
 10^5 (pointing to d_m)

$$\text{cond}(A) ? = \frac{10^5}{10^{-3}} = 10^8$$

2) $[Q, R] = \text{qr}(A)$

↓

$$A = Q \cdot R$$

orthogonal (circled) upper

$$M = \text{rand}(n, n)$$
$$[Q, R] = \text{qr}(M)$$

↳ random orthogonal matrix ...

Gauss / LU

Cholesky / $R \cdot R^T$
lower upper

Householder / QR

$$A \sim \begin{matrix} \text{diagonal} \\ \text{matrix} \end{matrix}$$
$$Q_n \times \dots \times Q_1$$

orthogonal / symmetric

3) $B = Q \times A$

$$\text{cond}(B) = \text{cond}(A)$$

10^8 ← can be chosen through the val. on the diag of A

solve syst.

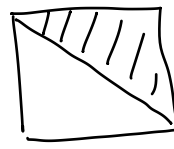
B

cond
⇒

~~~~~>

Gauss → LU

Householder → QR



cond ?

cond(B)

4) Cholesky  $\rightarrow$  ~~symmetric~~ definite positive matrices

$B = Q \times A$   
 (with  $Q$  orthogonal and  $A$  diagonal)

$B?$

$B^t = A^t \times Q^t$   
 $= A$

$Q^t = Q^{-1} \neq Q$

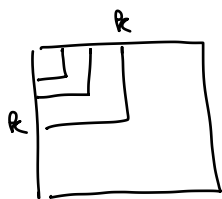
5)  $A$  — diag —  $\text{cond}(A) = c$   $\rightarrow A^t = A$

$B = Q \times A \times Q^t \rightarrow$  symmetric  $\checkmark$

Definite

positive  $\xrightarrow{\text{def}}$   $X^t \cdot M \cdot X > 0 \quad \forall X \neq 0$

eigenvalues of  $X^t \cdot M \cdot X > 0$



$\det(\text{sub } R \times R) > 0$

Let  $x \in \mathbb{R}^m$

$(x) \rightarrow X^t \cdot (Q \cdot A \cdot Q^t) \cdot X > 0!$   
 (with  $A$  diagonal and  $Q$  orthogonal)

$A = \begin{pmatrix} d_1 & & \\ & \ddots & \\ & & d_m \end{pmatrix} = \underbrace{\begin{pmatrix} \sqrt{d_1} & & \\ & \ddots & \\ & & \sqrt{d_m} \end{pmatrix}^t}_{R} \times \begin{pmatrix} \sqrt{d_1} & & \\ & \ddots & \\ & & \sqrt{d_m} \end{pmatrix}$   
 $d_i > 0$

$u^t \cdot x \cdot v = \langle u, v \rangle$   
 $\rightarrow u^t \cdot x \cdot u = \langle u, u \rangle = \|u\|^2$

$$(*) = \underbrace{X^t \cdot Q \cdot R^t}_{u^t} \cdot \underbrace{R \cdot Q^t \cdot X}_u = u^t \cdot x \cdot u = \|u\|^2 \geq 0 = ?$$

$u=0$

$$\cancel{R} \cdot \cancel{Q^t} \cdot X = 0$$

diag

$$\begin{pmatrix} \sqrt{d_1} & & \\ & \ddots & \\ & & \sqrt{d_m} \end{pmatrix}$$

$\downarrow$   
 $R^{-1} \checkmark$

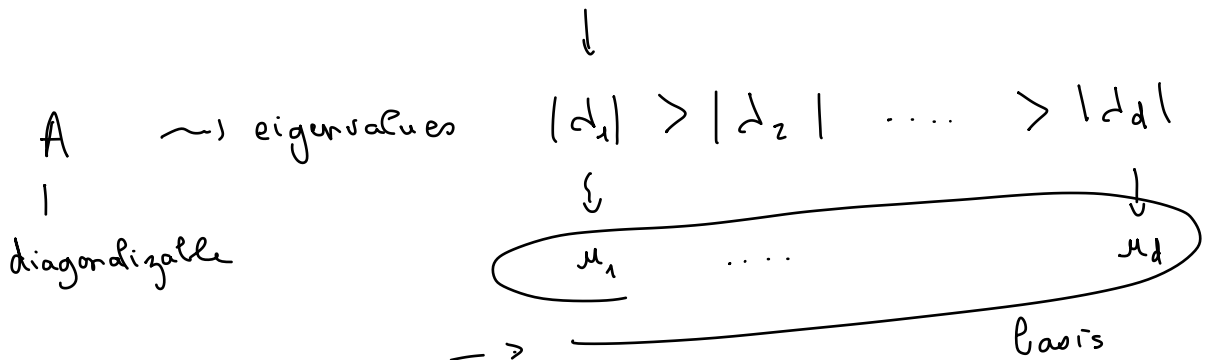
$Q$  is orthogonal  
 $\downarrow$   
 $Q^t = Q^{-1}$   
 invertible

$$u=0 \iff X=0$$

The matrix we have built is definite positive.

$$B = Q \cdot A \cdot Q^t \longrightarrow \text{norden-sym. def positive matrix cond. } \in \mathbb{R}$$

Ex. 2



$$\alpha_0 = \sum_i d_i \cdot \vec{u}_i$$

$$\alpha_m = A \cdot \alpha_{m-1}$$

$$\begin{aligned} \alpha_1 &= A \cdot \alpha_0 \\ &= A \left( \sum_i \alpha_i \vec{u}_i \right) \\ &= \sum_i \alpha_i \cdot \underbrace{A \vec{u}_i}_{d_i \cdot \vec{u}_i} \\ &= \sum_i \alpha_i \cdot d_i \cdot \vec{u}_i \end{aligned}$$

$$x_2 = A x_1 = A \left( \sum_i \alpha_i \overset{\mathbb{R}}{d_i} \overset{\mathbb{R}}{u_i} \right) = \sum_i \alpha_i \cdot d_i \cdot \underbrace{A u_i}_{d_i u_i} = \sum_i \alpha_i \cdot d_i^2 u_i$$

⋮

$$x_m = \sum_i \alpha_i \cdot d_i^m u_i$$

$$d_1 > d_2 \dots > d_d$$

Then

$$\frac{x_m}{d_1^m} = \sum_i \alpha_i \left( \frac{d_i}{d_1} \right)^m \cdot u_i$$

$$\left( \frac{d_i}{d_1} \right)^m \xrightarrow{m \rightarrow \infty} \begin{cases} 1 & i=1 \\ 0 & i>1 \end{cases}$$

$$d_i < d_1$$

$$\frac{x_m}{d_1^m} \xrightarrow{m \rightarrow \infty} \alpha_1 u_1$$

} first eigen vector.

Random diagonalizable matrix ←

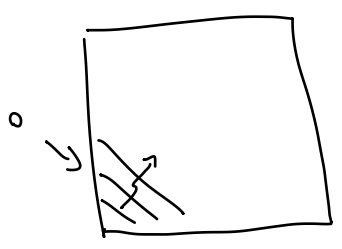
→ rand diag matrix A

→ rand base change

↑  
invert. matrix P

change basis  
↔

$P^{-1} \times A \times P$



↔

